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Data sheet for SINAMICS G120C

Article No. :

6SL3210-1KE17-5UP1



Figure similar

Client order no.	:
Order no. :	
Offer no. :	
Remarks :	

Rated data				
Input				
Number of phases	3 AC			
Line voltage	380 480 V +10 %	b -20 %		
Line frequency	47 63 Hz			
Rated current (LO)	9.50 A			
Rated current (HO)	8.20 A			
Output				
Number of phases	3 AC			
Rated voltage	400V IEC	480V NEC ¹⁾		
Rated power (LO)	3.00 kW	4.00 hp		
Rated power (HO)	2.20 kW	3.00 hp		
Rated current (LO)	7.30 A			
Rated current (HO)	5.60 A			
Rated current (IN)	7.50 A			
Max. output current	11.20 A			
Pulse frequency	4 kHz			
Output frequency for vector control	0 240 Hz			
Output frequency for V/f control	0 550 Hz			

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos \phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	52 dB	
Power loss	97.8 W	
Filter class (integrated)	Unfiltered	
Communication		
Communication		

Communication

PROFIBUS DP

ltem no. : Consignment no. : Project :

Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	1		
Output (resistive load)	DC 30 V, 0.5 A		
Number as transistor	1		
Output (resistive load)	DC 30 V, 0.5 A		
Analog / digital inputs			
Number	1 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
0→1	4 V		
1→0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$			
Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		

V/I ECO IIIIcal / square law	165
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

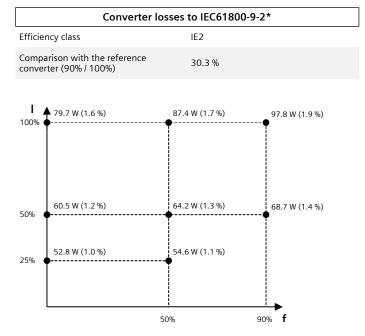
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Ambie	ent conditions	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.005 m³/s (0.177 ft³/s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Co	onnections	
Signal cable		
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Line side		
Version	Plug-in screw terminals	
Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
Motor end		
Version	Plug-in screw terminals	
Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
DC link (for braking resistor)		
Version	Plug-in screw terminals	
Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
Line length, max.	15 m (49.21 ft)	
PE connection	On housing with M4 screw	
Max. motor cable length		
Shielded	150 m (492.13 ft)	
Unshielded	150 m (492.13 ft)	
Mechanical data		
Degree of protection	IP20 / UL open type	
Frame size	FSA	
Net weight	1.70 kg (3.75 lb)	
Dimensions		
Width	73 mm (2.87 in)	
Height	196 mm (7.72 in)	
Depth	203 mm (7.99 in)	
Standards		
Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

 $^{1)}\mbox{The}$ output current and HP ratings are valid for the voltage range 440V-480V