

# **Data sheet for SINAMICS G120C**

Article No.: 6SL3210-1KE12-3UF2

Client order no. : Order no. : Offer no. : Remarks :





Figure simila

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 %	% -20 <b>%</b>
Line frequency	47 63 Hz	
Rated current (LO)	2.90 A	
Rated current (HO)	2.50 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC 1)
Rated power (LO)	0.75 kW	1.00 hp
Rated power (HO)	0.55 kW	0.75 hp
Rated current (LO)	2.20 A	
Rated current (HO)	1.70 A	
Rated current (IN)	2.30 A	
Max. output current	3.40 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

## Overload capability

Low Overload (LO)

 $150\,\%$  base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

Communication

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos\phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	49 dB	
Power loss	38.6 W	
Filter class (integrated)	Unfiltered	
Communication		

PROFINET, EtherNet/IP

Inputs / outputs	
Standard digital inputs	
Number	6
Switching level: 0→1	11 V
Switching level: 1→0	5 V
Max. inrush current	15 mA
Fail-safe digital inputs	
Number	1
Digital outputs	
Number as relay changeover contact	1
Output (resistive load)	DC 30 V, 0.5 A
Number as transistor	1
Output (resistive load)	DC 30 V, 0.5 A
Analog / digital inputs	
Number	1 (Differential input)
Resolution	10 bit
Switching threshold as digital input	
0→1	4 V
1→0	1.6 V
Analog outputs	
Number	1 (Non-isolated output)

#### PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy  $\pm 5\,^{\circ}\text{C}$ 

Closed-loop control techniques	
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No



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Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.005 m³/s (0.177 ft³/s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Connections		
Signal cable		
Conductor cross-section	0.15 1.50 mm <sup>2</sup> (AWG 24 AWG 16)	

Line side	

Version	Plug-in screw terminals
Conductor cross-section	1.00 2.50 mm <sup>2</sup> (AWG 18 AWG 14)

#### Motor end

Version	Plug-in screw terminals
Conductor cross-section	1.00 2.50 mm <sup>2</sup> (AWG 18 AWG 14)

# DC link (for braking resistor)

Version	Plug-in screw terminals
Conductor cross-section	1.00 2.50 mm <sup>2</sup> (AWG 18 AWG 14)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw

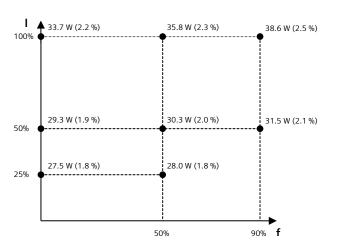
### Max. motor cable length

Shielded	150 m (492.13 ft)
Unshielded	150 m (492.13 ft)

I	Mechanical data	
Degree of protection	IP20 / UL open type	
Frame size	FSAA	
Net weight	1.40 kg (3.09 lb)	
Dimensions		
Width	73 mm (2.87 in)	
Height	173 mm (6.81 in)	
Depth	178 mm (7.01 in)	

Standards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low-





The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

<sup>\*</sup>calculated values

 $<sup>^{1)}</sup>$ The output current and HP ratings are valid for the voltage range 440V-480V