# SIEMENS

Data sheet for SINAMICS G120C

### Article No. :

### 6SL3210-1KE24-4AF1



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	41.00 A	
Rated current (HO)	39.00 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC <sup>1)</sup>
Rated power (LO)	22.00 kW	25.00 hp
Rated power (HO)	18.50 kW	20.00 hp
Rated current (LO)	43.00 A	
Rated current (HO)	37.00 A	
Rated current (IN)	43.00 A	
Max. output current	74.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

#### **Overload capability**

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor $\lambda$	0.90 0.95	
Offset factor $\cos \phi$	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	72 dB	
Power loss	699.0 W	
Filter class (integrated)	Class A	
Communication		

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	1		
Output (resistive load)	DC 30 V, 0.5 A		
Number as transistor	1		
Output (resistive load)	DC 30 V, 0.5 A		
Analog / digital inputs			
Number	1 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
0→1	4 V		
1→0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$			
Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		
Sensorless vector control	Yes		

Vector control, with sensor No Encoderless torque control No Torque control, with encoder No

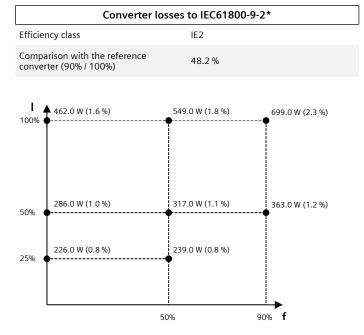
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Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.055 m³/s (1.942 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 40 °C (-4 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			
Max. operation	95 % RH, condensation not permitted		
(	Connections		
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)		
Motor end			
Version	Screw-type terminals		
Version	10.00 35.00 mm <sup>2</sup>		
Conductor cross-section	(AWG 8 AWG 2)		
DC link (for braking resistor)			
Version	Screw-type terminals		
Conductor cross-section	10.00 35.00 mm <sup>2</sup> (AWG 8 AWG 2)		
Line length, max.	10 m (32.81 ft)		
PE connection	Screw-type terminals		
Max. motor cable length			
Shielded	200 m (656.17 ft)		
Unshielded	300 m (984.25 ft)		
Mechanical data			
Degree of protection	IP20 / UL open type		
Frame size	FSD		
Net weight	18.80 kg (41.45 lb)		
Dimensions			
Width	200 mm (7.87 in)		
Height	472 mm (18.58 in)		
Depth	237 mm (9.33 in)		
	Standards		
Compliance with standards	UL, cUL, CE, C-Tick (RCM)		
CE marking EMC Directive 2004/108/EC, Low Voltage Directive 2006/95/EC			



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

\*calculated values

 $^{1)}\mbox{The}$  output current and HP ratings are valid for the voltage range 440V-480V