# SIEMENS

Data sheet for SINAMICS G120C

### Article No. :

# 6SL3210-1KE21-3AB1



Figure similar

Client order no.	•
Order no. :	
Offer no. :	
Remarks :	

Rated data		
3 AC		
380 480 V +10 %	‰ -20 %	
47 63 Hz		
16.50 A		
12.80 A		
3 AC		
400V IEC	480V NEC <sup>1)</sup>	
5.50 kW	7.50 hp	
4.00 kW	5.00 hp	
12.50 A		
8.80 A		
13.00 A		
17.60 A		
4 kHz		
0 240 Hz		
0 550 Hz		
	3 AC 380 480 V +10 % 47 63 Hz 16.50 A 12.80 A 12.80 A 3 AC 400V IEC 5.50 kW 4.00 kW 12.50 A 8.80 A 13.00 A 17.60 A 17.60 A 4 kHz 0 240 Hz	

### Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor $\lambda$	0.70 0.85	
Offset factor $\cos \phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	63 dB	
Power loss	173.0 W	
Filter class (integrated)	Class A	
Communication		

Communication

USS/MODBUS RTU

ltem no. : Consignment no. : Project :

Inputs / outputs				
Standard digital inputs				
Number	6			
Switching level: $0 \rightarrow 1$	11 V			
Switching level: $1 \rightarrow 0$	5 V			
Max. inrush current	15 mA			
Fail-safe digital inputs				
Number	1			
Digital outputs				
Number as relay changeover contact	1			
Output (resistive load)	DC 30 V, 0.5 A			
Number as transistor	1			
Output (resistive load)	DC 30 V, 0.5 A			
Analog / digital inputs				
Number	1 (Differential input)			
Resolution	10 bit			
Switching threshold as digital input				
0→1	4 V			
1→0	1.6 V			
Analog outputs				
Number	1 (Non-isolated output)			
PTC/ KTY interface				
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$				
Closed-loop control techniques				
V/f linear / square-law / parameterizable	Yes			
V/f with flux current control (FCC)	Yes			

VIT WITH HUX CUITERIC CONTION (FCC)	165
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

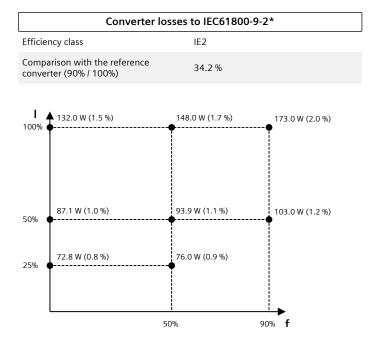
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Ambien	t conditions
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.009 m³/s (0.318 ft³/s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Con	nections
Signal cable	
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Line side	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Motor end	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
DC link (for braking resistor)	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw
Max. motor cable length	
Shielded	50 m (164.04 ft)
Unshielded	100 m (328.08 ft)
Mecha	anical data
Degree of protection	IP20 / UL open type
Frame size	FSB
Net weight	2.30 kg (5.07 lb)
Dimensions	
Width	100 mm (3.94 in)
Height	196 mm (7.72 in)
Depth	203 mm (7.99 in)
Sta	andards
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

\*calculated values

<sup>1)</sup>The output current and HP ratings are valid for the voltage range 440V-480V