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Data sheet for SINAMICS G120C

Article No. :

6SL3210-1KE21-3UF1



Figure similar

Client order no.	
Order no. :	
Offer no. :	
Remarks :	

Rated data				
Input				
Number of phases	3 AC			
Line voltage	380 480 V +10 %	b -20 %		
Line frequency	47 63 Hz			
Rated current (LO)	16.50 A			
Rated current (HO)	12.80 A			
Output				
Number of phases	3 AC			
Rated voltage	400V IEC	480V NEC ¹⁾		
Rated power (LO)	5.50 kW	7.50 hp		
Rated power (HO)	4.00 kW	5.00 hp		
Rated current (LO)	12.50 A			
Rated current (HO)	8.80 A			
Rated current (IN)	13.00 A			
Max. output current	17.60 A			
Pulse frequency	4 kHz			
Output frequency for vector control	0 240 Hz			
Output frequency for V/f control	0 550 Hz			

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos \phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	63 dB	
Power loss	169.0 W	
Filter class (integrated)	Unfiltered	
Communication		

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Inputs / outputs					
Standard digital inputs					
Number	6				
Switching level: $0 \rightarrow 1$	11 V				
Switching level: $1 \rightarrow 0$	5 V				
Max. inrush current	15 mA				
Fail-safe digital inputs					
Number	1				
Digital outputs					
Number as relay changeover contact	1				
Output (resistive load)	DC 30 V, 0.5 A				
Number as transistor	1				
Output (resistive load)	DC 30 V, 0.5 A				
Analog / digital inputs					
Number	1 (Differential input)				
Resolution	10 bit				
Switching threshold as digital input					
0→1	4 V				
1→0	1.6 V				
Analog outputs					
Number	1 (Non-isolated output)				
PTC/ KTY interface					
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$					
Closed-loop control techniques					
V/f linear / square-law / parameterizable	Yes				
V/f with flux current control (FCC)	Yes				
V/f ECO linear / square-law	Yes				
Sensorless vector control	Yes				

Vector control, with sensor No Encoderless torque control No Torque control, with encoder No

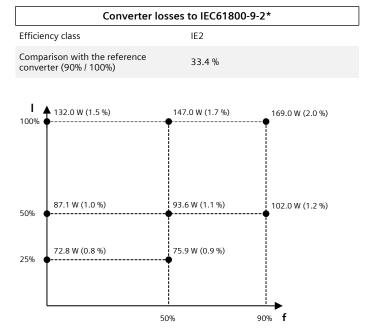
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Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.009 m³/s (0.318 ft³/s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Co	onnections	
Signal cable		
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Line side		
Version	Plug-in screw terminals	
Conductor cross-section	4.00 6.00 mm ² (AWG 12 AWG 10)	
Motor end		
Version	Plug-in screw terminals	
Conductor cross-section	4.00 6.00 mm ² (AWG 12 AWG 10)	
DC link (for braking resistor)		
Version	Plug-in screw terminals	
Conductor cross-section	4.00 6.00 mm ² (AWG 12 AWG 10)	
Line length, max.	15 m (49.21 ft)	
PE connection	On housing with M4 screw	
Max. motor cable length		
Shielded	150 m (492.13 ft)	
Unshielded	150 m (492.13 ft)	
Мес	hanical data	
Degree of protection	IP20 / UL open type	
Frame size	FSB	
Net weight	2.30 kg (5.07 lb)	
Dimensions		
Width	100 mm (3.94 in)	
Height	196 mm (7.72 in)	
Depth	208 mm (8.19 in)	
S	itandards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

 $^{\rm 1)} {\rm The}$ output current and HP ratings are valid for the voltage range 440V-480V