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Data sheet for SINAMICS G120C

Article No. :

6SL3210-1KE21-7UB1



Figure similar

Client order no.	
Order no. :	
Offer no. :	
Remarks :	

Rated data				
Input				
Number of phases	3 AC			
Line voltage	380 480 V +10 %	% -20 %		
Line frequency	47 63 Hz			
Rated current (LO)	21.50 A			
Rated current (HO)	18.20 A			
Output				
Number of phases	3 AC			
Rated voltage	400V IEC	480V NEC ¹⁾		
Rated power (LO)	7.50 kW	10.00 hp		
Rated power (HO)	5.50 kW	7.50 hp		
Rated current (LO)	16.50 A			
Rated current (HO)	12.50 A			
Rated current (IN)	17.00 A			
Max. output current	25.00 A			
Pulse frequency	4 kHz			
Output frequency for vector control	0 240 Hz			
Output frequency for V/f control	0 550 Hz			

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications			
Power factor λ	0.70 0.85		
Offset factor $\cos \phi$	0.95		
Efficiency η	0.97		
Sound pressure level (1m)	63 dB		
Power loss	228.0 W		
Filter class (integrated)	Unfiltered		
Communication			

Communication

USS/MODBUS RTU

ltem no. : Consignment no. : Project :

Inputs / outputs					
Standard digital inputs					
Number	6				
Switching level: $0 \rightarrow 1$	11 V				
Switching level: $1 \rightarrow 0$	5 V				
Max. inrush current	15 mA				
Fail-safe digital inputs					
Number	1				
Digital outputs					
Number as relay changeover contact	1				
Output (resistive load)	DC 30 V, 0.5 A				
Number as transistor	1				
Output (resistive load)	DC 30 V, 0.5 A				
Analog / digital inputs					
Number	1 (Differential input)				
Resolution	10 bit				
Switching threshold as digital input					
0→1	4 V				
1→0	1.6 V				
Analog outputs					
Number	1 (Non-isolated output)				
PTC/ KTY interface					
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$					
Closed-loop control techniques					
V/f linear / square-law / parameterizable	Yes				
V/f with flux current control (FCC)	Yes				
V/f ECO linear / square-law	Yes				
Sensorless vector control	Yes				

No

Encoderless torque control No Torque control, with encoder No

Vector control, with sensor

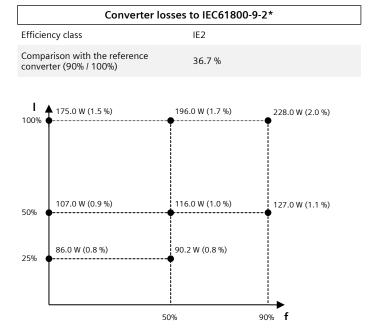
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Ambi	ent conditions
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.009 m³/s (0.318 ft³/s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Co	onnections
Signal cable	
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Line side	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm ² (AWG 12 AWG 10)
Motor end	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm ² (AWG 12 AWG 10)
DC link (for braking resistor)	
Version	Plug-in screw terminals
Conductor cross-section	4.00 6.00 mm ² (AWG 12 AWG 10)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw
Max. motor cable length	
Shielded	150 m (492.13 ft)
Unshielded	150 m (492.13 ft)
Mec	hanical data
Degree of protection	IP20 / UL open type
Frame size	FSB
Net weight	2.30 kg (5.07 lb)
Dimensions	
Width	100 mm (3.94 in)
Height	196 mm (7.72 in)
Depth	203 mm (7.99 in)
	Standards
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

 $^{1)}\mbox{The}$ output current and HP ratings are valid for the voltage range 440V-480V