

Data sheet for SINAMICS G120C

Article No.: 6SL3210-1KE23-2UB1

Client order no. : Order no. : Offer no. : Remarks :



Number

Number

PTC/ KTY interface

Standard digital inputs



Figure similar

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 %	% -20 %
Line frequency	47 63 Hz	
Rated current (LO)	40.60 A	
Rated current (HO)	36.40 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC 1)
Rated power (LO)	15.00 kW	20.00 hp
Rated power (HO)	11.00 kW	15.00 hp
Rated current (LO)	31.00 A	
Rated current (HO)	25.00 A	
Rated current (IN)	32.00 A	
Max. output current	50.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload	capability
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Low Overload (LO)

 $150\,\%$ base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

Communication

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications	
Power factor λ	0.70 0.85
Offset factor $\cos\phi$	0.95
Efficiency η	0.97
Sound pressure level (1m)	66 dB
Power loss	361.0 W
Filter class (integrated)	Unfiltered
Communication	

USS/MODBUS RTU

Switching level: 0→1	11 V
Switching level: 1→0	5 V
Max. inrush current	15 mA
Fail-safe digital inputs	
Number	1
Digital outputs	
Number as relay changeover contact	1
Output (resistive load)	DC 30 V, 0.5 A
Number as transistor	1
Output (resistive load)	DC 30 V, 0.5 A
Analog / digital inputs	
Number	1 (Differential input)
Resolution	10 bit
Switching threshold as digital input	
0→1	4 V
1→0	1.6 V
Analog outputs	

Inputs / outputs

6

Closed-loop control techniques V/f linear / square-law / parameterizable Yes V/f with flux current control (FCC) Yes V/f ECO linear / square-law Yes Sensorless vector control Yes Vector control, with sensor No Encoderless torque control No Torque control, with encoder No

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

1 (Non-isolated output)



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Δml	pient conditions
Cooling Air cooling using an integrated fan	
Cooling air requirement	0.018 m ³ /s (0.636 ft ³ /s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	1,000 III (3,200.64 It)
Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
·	-40 70 °C (-40 158 °F)
Storage	-40 70 C (-40 136 F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
	Connections
Signal cable	
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)
Line side	

Motor	end

Version

Version	Plug-in screw terminals
Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)

Plug-in screw terminals

6.00 ... 16.00 mm²

(AWG 10 ... AWG 6)

DC link (for braking resistor)

Conductor cross-section

Version	Plug-in screw terminals
Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw

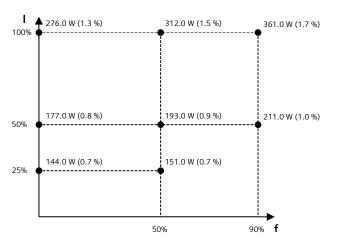
Max. motor cable length

Shielded	150 m (492.13 ft)
Unshielded	150 m (492.13 ft)

Mechanical data	
Degree of protection	IP20 / UL open type
Frame size	FSC
Net weight	4.40 kg (9.70 lb)
Dimensions	
Width	140 mm (5.51 in)
Height	295 mm (11.61 in)
Depth	203 mm (7.99 in)

Standards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low-

Converter losses to IEC61800-9-2*	
Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	33.3 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

^{*}calculated values

 $^{^{1)}}$ The output current and HP ratings are valid for the voltage range 440V-480V