



MLFB-Ordering data 1FK7100-3BC71-1RB0

Client order no. :
Order no. :
Offer no. :
Remarks :

Item no. :
Consignment no. :
Project :

Engineering data		Mechanical data	
Rated speed (100 K)	2000 rpm	Motor type	Permanent-magnet synchronous motor
Number of poles	8	Motor type	High Inertia
Rated torque (100 K)	14.5 Nm	Shaft height	100
Rated current	7.1 A	Cooling	Natural cooling
Static torque (60 K)	14.90 Nm	Radial runout tolerance	0.050 mm
Static torque (100 K)	18.00 Nm	Concentricity tolerance	0.10 mm
Stall current (60 K)	6.80 A	Axial runout tolerance	0.10 mm
Stall current (100 K)	8.40 A	Vibration severity grade	Grade A
Moment of inertia	95.000 kgcm²	Connector size	1
Efficiency	92.0 %	Degree of protection	IP64
Physical constants		Design acc. to Code I	IM B5 (IM V1, IM V3)
Torque constant	2.14 Nm/A	Temperature monitoring	Pt1000 temperature sensor
Voltage constant at 20° C	138.0 V/1000*min ⁻¹	Electrical connectors	Connectors for signals and power rotatable
Winding resistance at 20° C	0.55 Ω	Color of the housing	Standard (Anthracite RAL 7016)
Rotating field inductance	12.7 mH	Holding brake	with holding brake
Electrical time constant	23.00 ms	Shaft end	Feather key
Mechanical time constant	3.15 ms	Encoder system	Encoder AM20DQI: absolute encoder 20 bits (resolution 1048576, encoder-internal 512 S/R) + 12 bits multi-turn (traversing range 4096 revolutions)
Thermal time constant	55 min		
Shaft torsional stiffness	135000 Nm/rad		
Net weight of the motor	22.8 kg		



Figure similar

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Optimum operating point		Recommended Motor Module	
Optimum speed	2000 rpm	Rated inverter current	9 A
Optimum power	3.0 kW	Maximum inverter current	27 A
Limiting data		Maximum torque	53.40 Nm
Max. permissible speed (mech.)	5000 rpm		
Max. permissible speed (inverter)	4200 rpm		
Maximum torque	55.0 Nm		
Maximum current	28.0 A		
Holding brake			
Holding brake version	Permanent-magnet brake		
Holding torque	23.0 Nm		
Power supply voltage	DC 24 V ± 10 %		
Coil current	1.0 A		
Opening time	300 ms		
Closing time	70 ms		
Highest braking work	3380 J		