

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV3082A

SIMOTICS GP - 80 M - IM B5 - 2p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks	Safe Area
Electrical data	-/-

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL		
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N			
DOL duty (S1) - 155(F) to 130(B)																			
230	Δ	50	0.75	-/-	2.70	2850	2.5	80.7	82.2	81.9	0.86	0.82	0.73	6.2	2.6	3.0	IE3		
400	Y	50	0.75	-/-	1.56	2850	2.5	80.7	82.2	81.9	0.86	0.82	0.73	6.2	2.6	3.0	IE3		
460	Y	60	0.86	-/-	1.63	3450	2.4	77.0	78.0	77.2	0.86	0.82	0.73	6.4	2.6	3.1	IE3		
460	Y	60	0.75	-/-	1.45	3480	2.0	77.0	77.2	75.7	0.84	0.79	0.70	7.1	3.0	3.6	IE3		
IM B5 / IM 3001				FS 80 M				IP55		UKCA		IEC/EN 60034			IEC, DIN, ISO, VDE, EN				
Environmental conditions : -20 °C - +40 °C / 1000 m									Locked rotor time (hot / cold) : 21.2 s 27.9 s										

Mechanical data				
Sound level (SPL / SWL) at 50Hz 60Hz	60 / 71 dB(A) ^{2) 3)}	64 / 75 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0011 kg m²		Thermal class	F
Bearing DE NDE	6004 2Z C3	6004 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Regreasing device	Without		Net weight of the motor (IM B3)	11 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Preloaded bearing DE		Color, paint shade	RAL7030
Condensate drainage holes	Without		Motor protection	(A) without (Standard)
External earthing terminal	Without		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box																	
Terminal box position			top			Max. cross-sectional area			1.5 mm²								
Material of terminal box			Aluminium			Cable diameter from ... to ...			9 mm - 17 mm								
Type of terminal box			TB1 E00			Cable entry			1xM25x1,5								
Contact screw thread			M4			Cable gland			1 plug								

I_A/I_N = locked rotor current / current nominal
M_K/M_N = locked rotor torque / torque nominal
M_B/M_N = break down torque / nominal torque

1) L_{10mh} according to DIN ISO 281 10/2010
2) at rated power / at full load

3) Value is valid only for DOL operation with motor design IC411

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