## Data sheet for SINAMICS G120C

## Article No. : <br> 6SL3210-1KE22-6AC1



Client order no. :
Order no. :
Offer no. :
Remarks :

|  | Rated data |
| :--- | :--- |
| Input |  |
| Number of phases | 3 AC |
| Line voltage | $380 \ldots 480 \mathrm{~V}+10 \%-20 \%$ |
| Line frequency | $47 \ldots 63 \mathrm{~Hz}$ |
| Rated current (LO) | 33.00 A |
| Rated current (HO) | 24.10 A |

Output

| Number of phases | 3 AC |  |
| :--- | :--- | :--- |
| Rated voltage | 400 V IEC | 480 V NEC ${ }^{1)}$ |
| Rated power (LO) | 11.00 kW | 15.00 hp |
| Rated power (HO) | 7.50 kW | 10.00 hp |
| Rated current (LO) | 25.00 A |  |
| Rated current (HO) | 16.50 A |  |
| Rated current (IN) | 26.00 A |  |
| Max. output current | 33.00 A |  |
| Pulse frequency | 4 kHz |  |
| Output frequency for vector control | $0 \ldots 240 \mathrm{~Hz}$ |  |
| Output frequency for V/f control | $0 \ldots 550 \mathrm{~Hz}$ |  |

Overload capability
Low Overload (LO)
150 \% base load current IL for 3 s, followed by $110 \%$ base load current IL for 57 s in a 300 s cycle time

High Overload (HO)
$200 \%$ base load current IH for 3 s, followed by $150 \%$ base load current IH for 57 s in a 300 s cycle time

|  | General tech. specifications |
| :--- | :--- |
| Power factor $\lambda$ | $0.70 \ldots 0.85$ |
| Offset factor $\cos \varphi$ | 0.95 |
| Efficiency $\eta$ | 0.97 |
| Sound pressure level (1m) | 66 dB |
| Power loss | 298.0 W |
| Filter class (integrated) | Class A |
|  | Communication |

Communication
CANopen

Item no. :
Consignment no. :
Project :
Inputs / outputs

Standard digital inputs

| Number | 6 |
| :--- | :--- |
| Switching level: $0 \rightarrow 1$ | 11 V |
| Switching level: $1 \rightarrow 0$ | 5 V |
| Max. inrush current | 15 mA |

Fail-safe digital inputs
Number 1

## Digital outputs

| Number as relay changeover contact | 1 |
| :--- | :--- |
| Output (resistive load) | DC $30 \mathrm{~V}, 0.5 \mathrm{~A}$ |
| Number as transistor | 1 |
| Output (resistive load) | DC $30 \mathrm{~V}, 0.5 \mathrm{~A}$ |

Analog / digital inputs

| Number | 1 (Differential input) |
| :--- | :--- |
| Resolution | 10 bit |

Switching threshold as digital input

| $0 \rightarrow 1$ | 4 V |
| :--- | :--- |
| $1 \rightarrow 0$ | 1.6 V |

Analog outputs
Number 1 (Non-isolated output)

## PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5^{\circ} \mathrm{C}$

## Closed-loop control techniques

V/f linear / square-law / parameterizable Yes

| V/f with flux current control (FCC) | Yes |
| :--- | :--- |
| V/f ECO linear / square-law | Yes |
| Sensorless vector control | Yes |
| Vector control, with sensor | No |
| Encoderless torque control | No |
| Torque control, with encoder | No |

## Data sheet for SINAMICS G120C

## Article No. :

6SL3210-1KE22-6AC1

| Converter losses to IEC61800-9-2* |  |
| :--- | :---: |
| Efficiency class IE2 <br> Comparison with the reference <br> converter (90\% / 100\%) $33.2 \%$ |  |



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency $(f)$. The values are valid for the basic version of the converter without options/components.
*calculated values

[^0]
[^0]:    ${ }^{1)}$ The output current and HP ratings are valid for the voltage range 440V-480V

